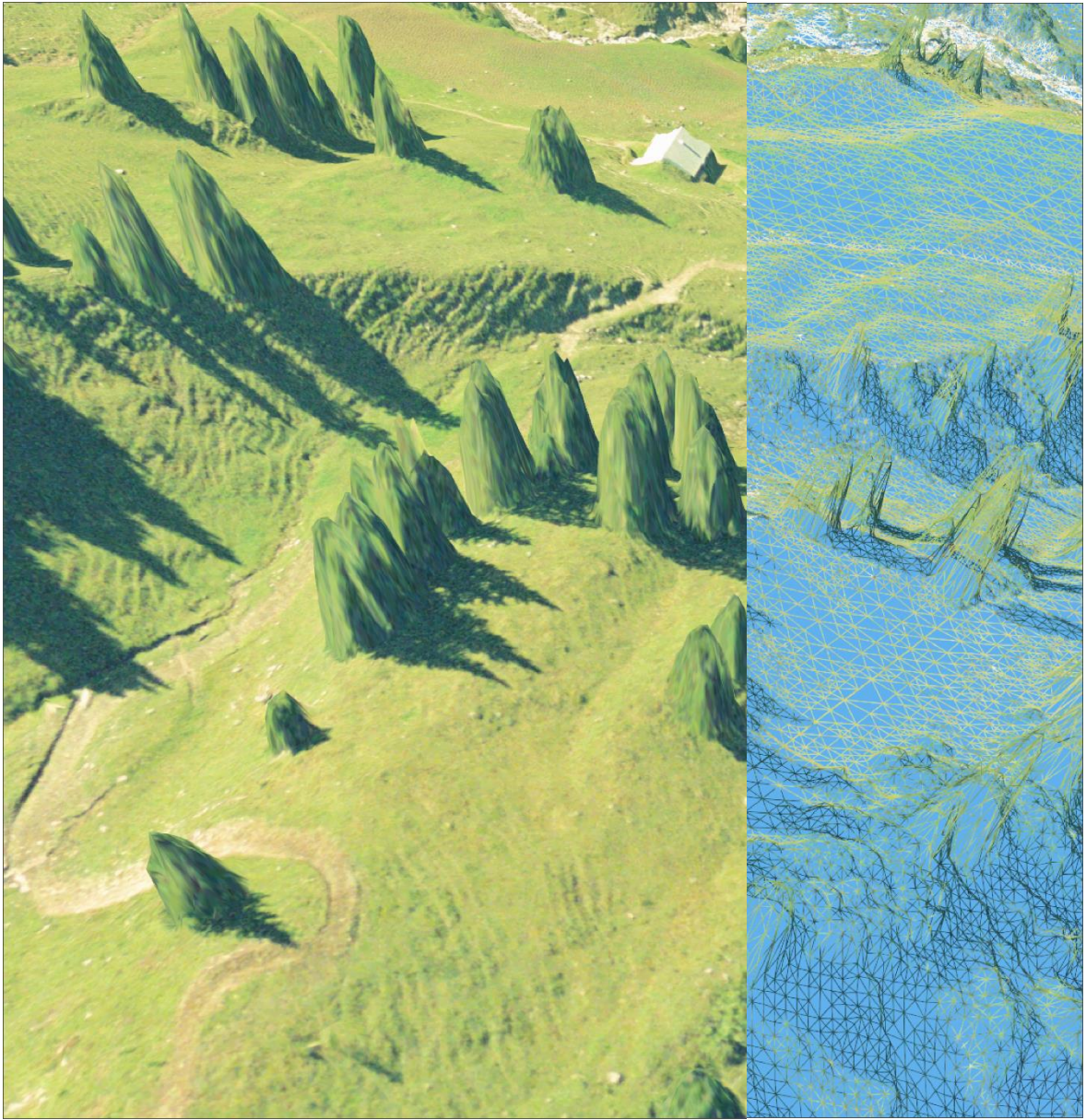


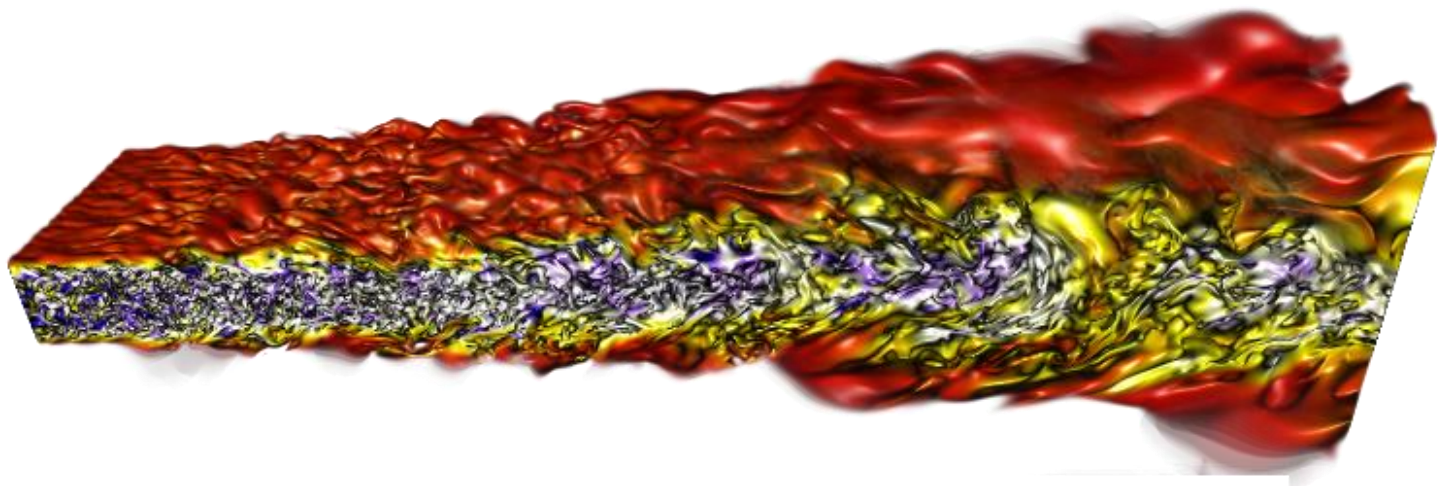
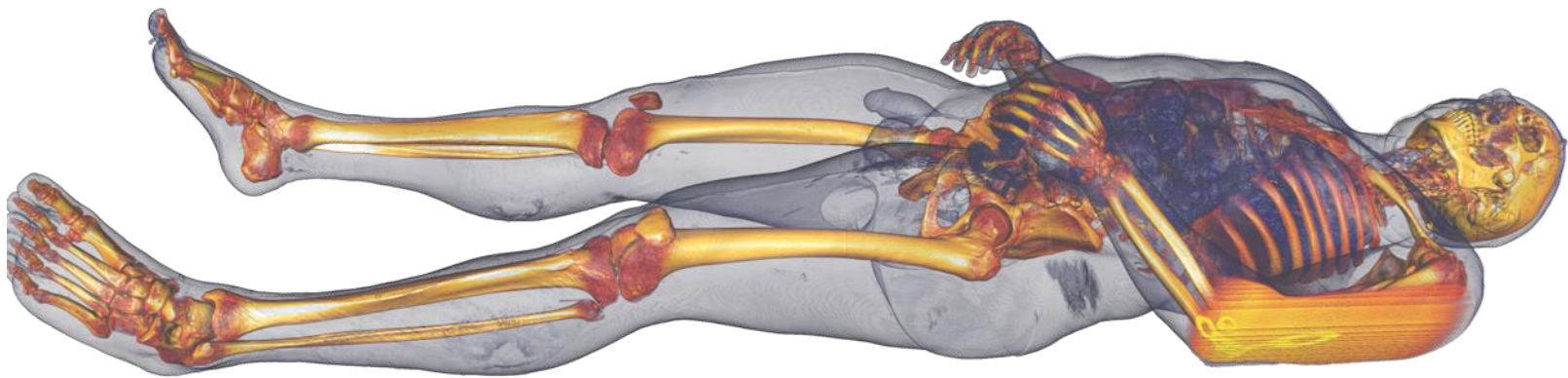


Visualization, DD2257
Prof. Dr. Tino Weinkauff

Data Description

Sampled Data

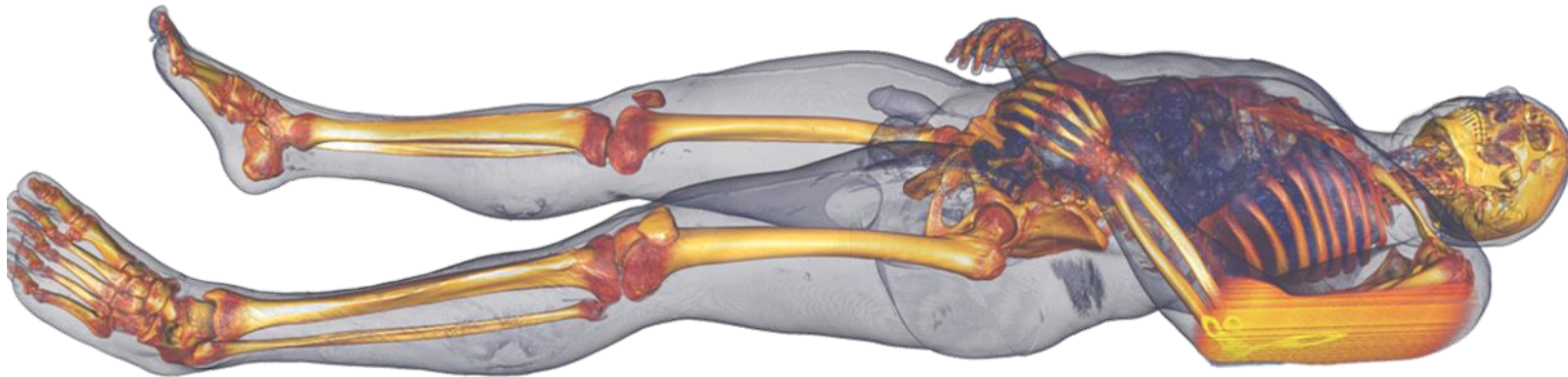
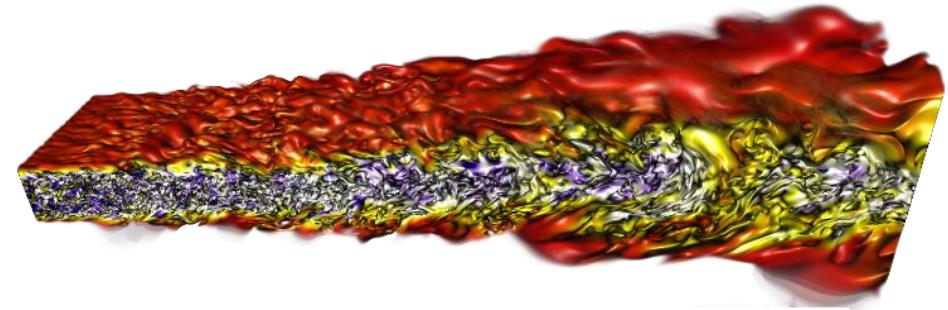
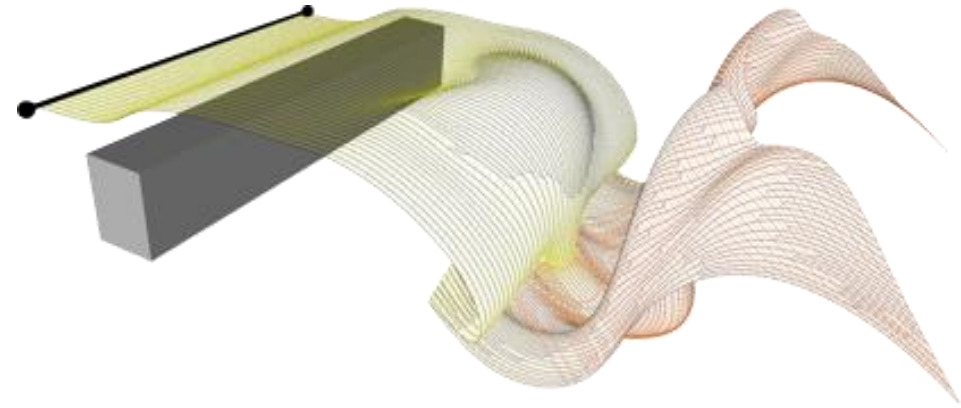




- In most cases, the visualization data represents a **continuous real object**, e.g., an oscillating membrane, a velocity field around a body, an organ, human tissue, etc.
 - This object lives in an n-dimensional space - the **domain** (aka. observation space)
- Usually, the data is only given at a finite set of locations, or **samples**, in space and/or time
 - Remember imaging processes like numerical simulation and CT-scanning, note similarity to pixel images
- We call this a **discrete representation** of a continuous object

Discrete Representations

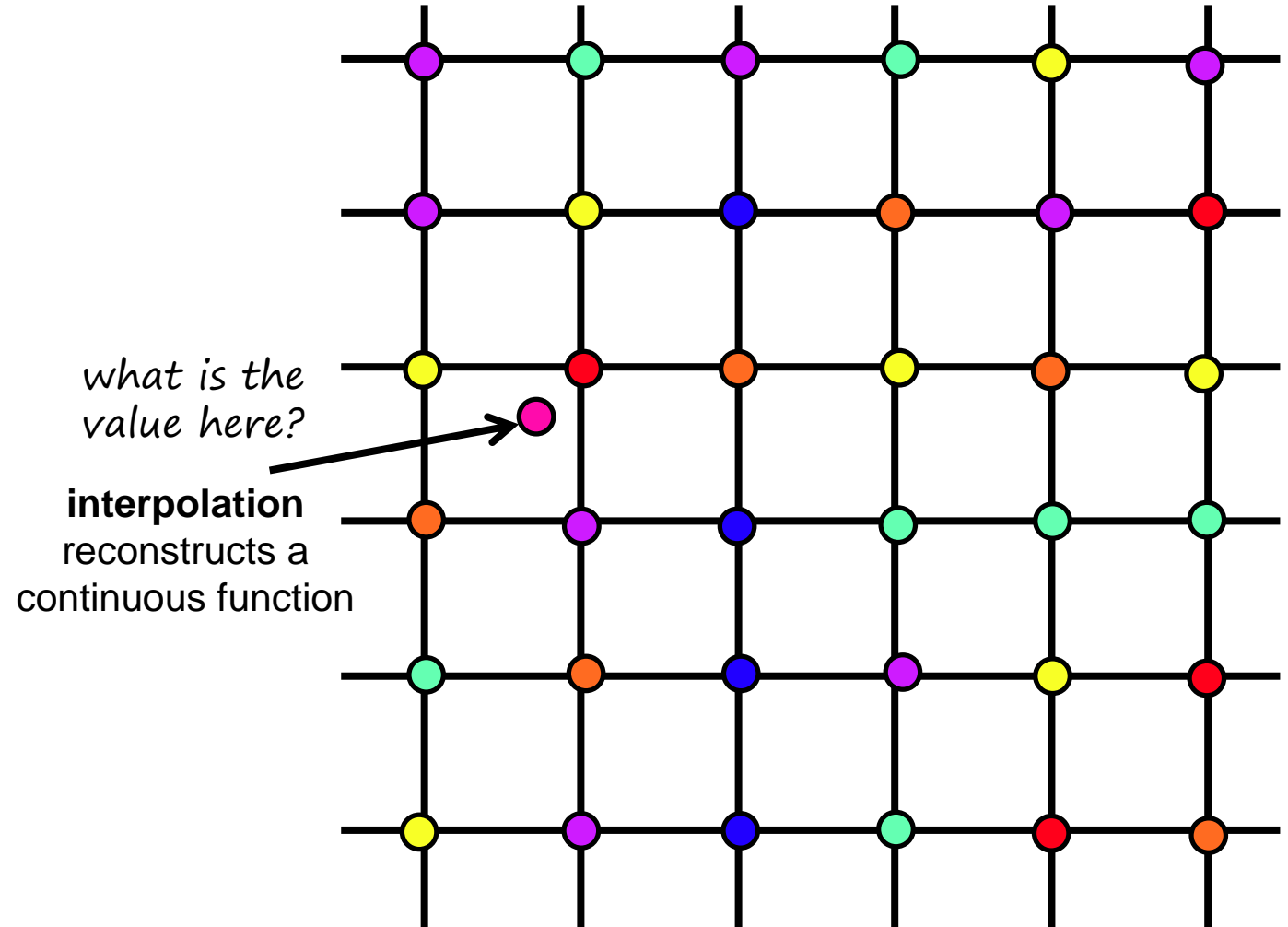
We usually deal with the **reconstruction** of a continuous real object from a given discrete representation.



Discrete Representations

We usually deal with the **reconstruction** of a continuous real object from a given discrete representation.

Samples are connected to each other to form **grids / meshes**, covering the entire domain.



Grid terminology

grid cell: largest-dimensional element in a grid

2D: grid face

3D: grid voxel

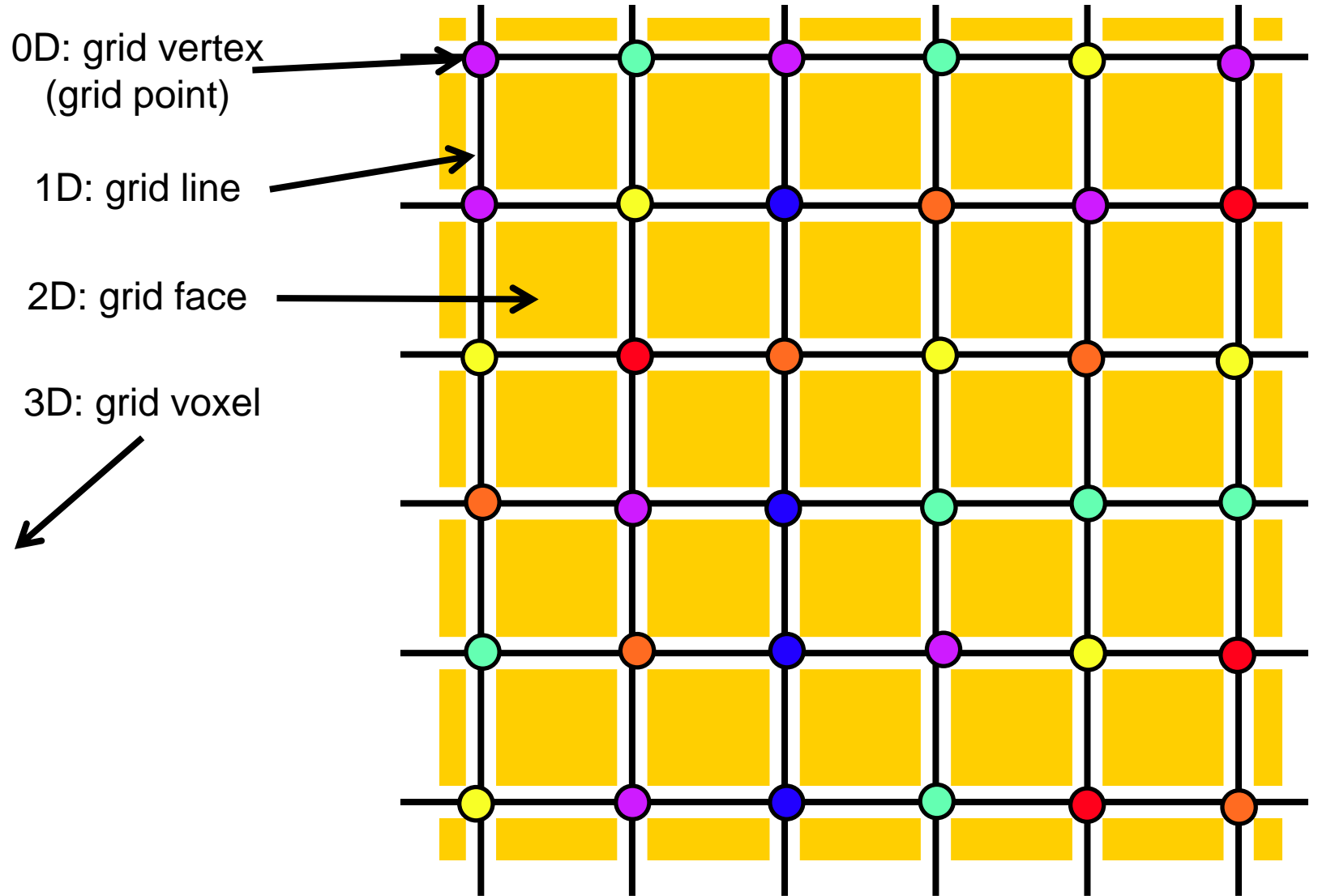
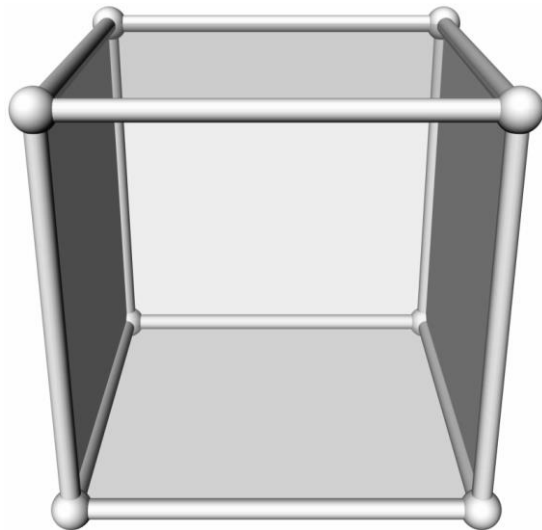
0D: grid vertex
(grid point)

1D: grid line

2D: grid face

3D: grid voxel

grid vertices
grid lines
grid faces
grid voxel



Operations on Grids

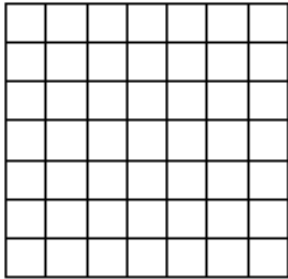
- Determine the **data value** at a position
 - Easy at the grid vertices
 - At other positions: Interpolation Schemes
- Determine neighbors
- Convert to other grid types
- Compute metrics
 - Distance, Area, Volume
- Compute Bounding Box

Data Connectivity

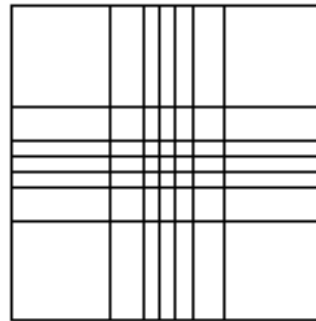
- There are different types of grids:
- **Structured grids**
connectivity is implicitly given.
 - **Block-structured grids**
combination of several structured grids
- **Unstructured grids**
connectivity is explicitly given.
- **Hybrid grids**
combination of different grid types

Structured grids

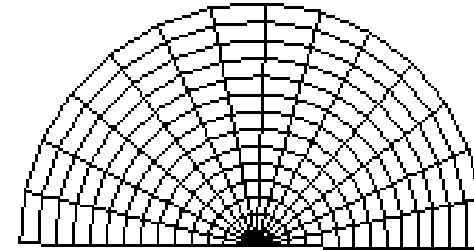
- “Structured” refers to the matrix-like connectivity between the grid vertices
- We distinguish different types of structured grids regarding the alignment to the coordinate system and the size of cells



uniform grid
*axis-aligned, identical cells
implicitly given coordinates*



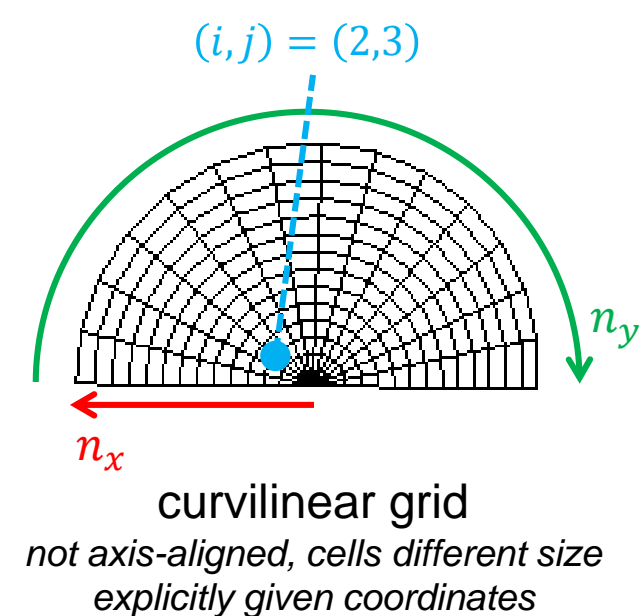
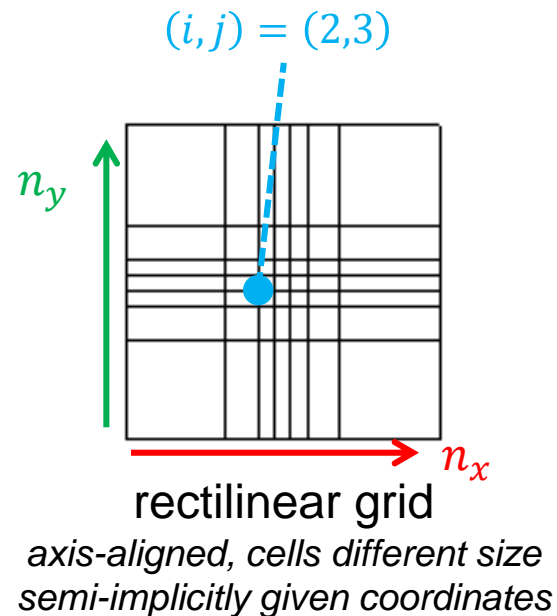
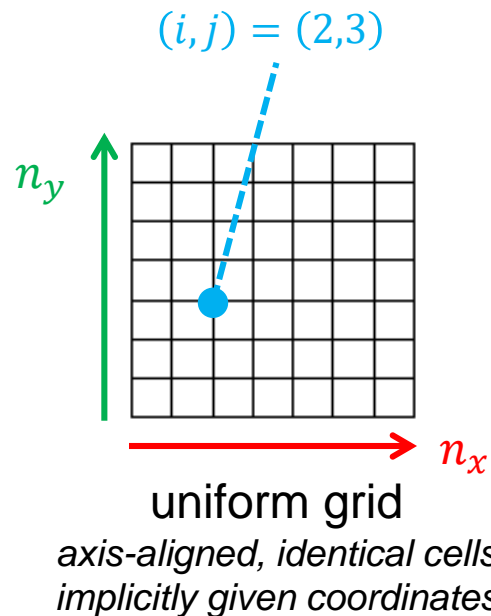
rectilinear grid
*axis-aligned, cells different size
semi-implicitly given coordinates*



curvilinear grid
*not axis-aligned, cells different size
explicitly given coordinates*

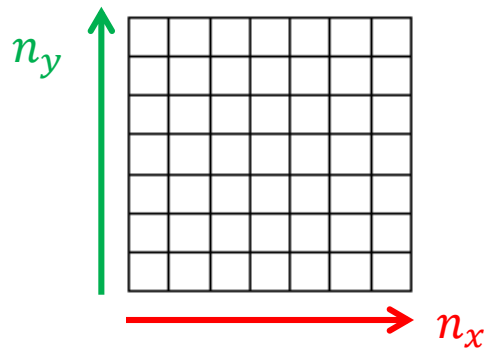
Structured grids

- Number of grid vertices: n_x, n_y, n_z
- We can address every **grid vertex** with an index tuple (i, j, k)
 - $0 \leq i < n_x$ $0 \leq j < n_y$ $0 \leq k < n_z$

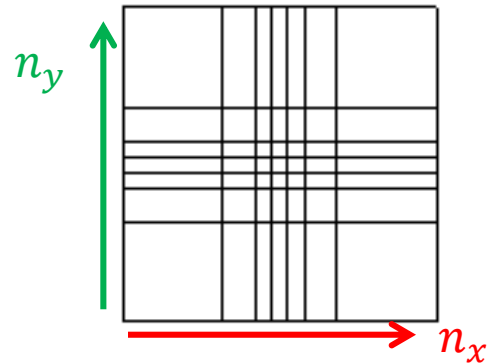


Structured grids

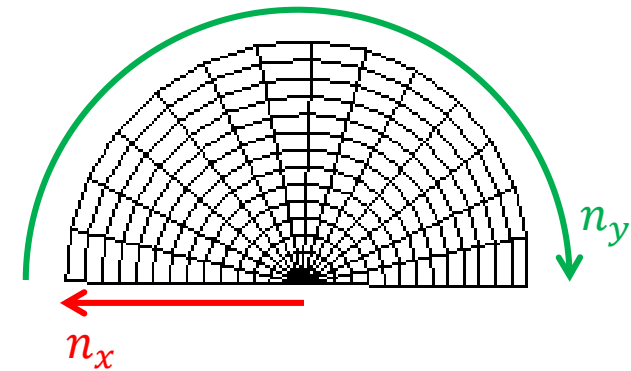
- Number of grid vertices: n_x, n_y, n_z
- We can address every **grid cell** with an index tuple (i, j, k)
 - $0 \leq i < n_x - 1$ $0 \leq j < n_y - 1$ $0 \leq k < n_z - 1$
- ➔ Number of cells: $(n_x - 1) \times (n_y - 1) \times (n_z - 1)$



uniform grid
axis-aligned, identical cells
implicitly given coordinates



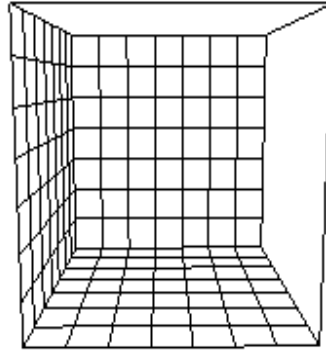
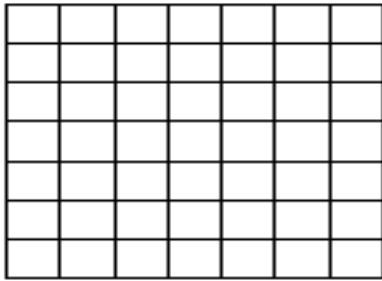
rectilinear grid
axis-aligned, cells different size
semi-implicitly given coordinates



curvilinear grid
not axis-aligned, cells different size
explicitly given coordinates

Regular or uniform grids

- Cells are rectangles or rectangular cuboids of the same size
- All grid lines are parallel to the axes

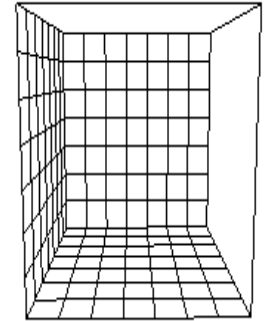
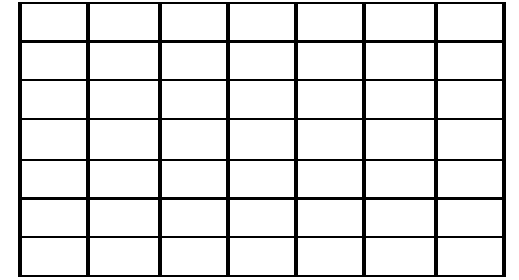


- To define a uniform grid, we need the following:
 - Bounding box: $(x_{min}, y_{min}, z_{min}) - (x_{max}, y_{max}, z_{max})$
 - Number of grid vertices in each dimension: n_x, n_y, n_z
- from that information we can derive the Cell size: d_x, d_y, d_z

Regular or uniform grids

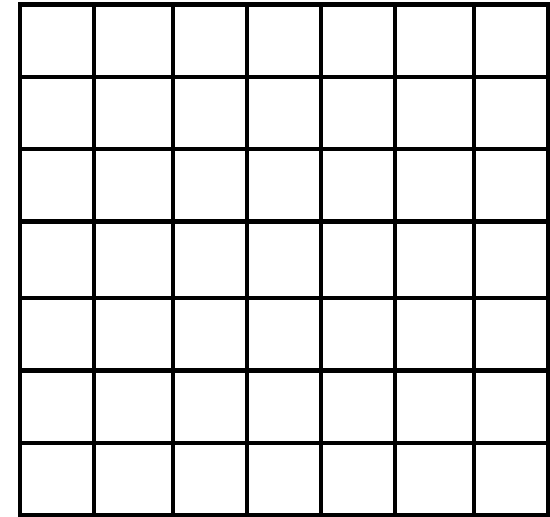
- Well suited for image data (medical applications)
- Coordinate \rightarrow cell is very simple and cheap
 - Global search is good enough; local search not required
- Coordinate of a grid vertex:

$$(i \cdot d_x, j \cdot d_y, k \cdot d_z) + (x_{min}, y_{min}, z_{min})$$



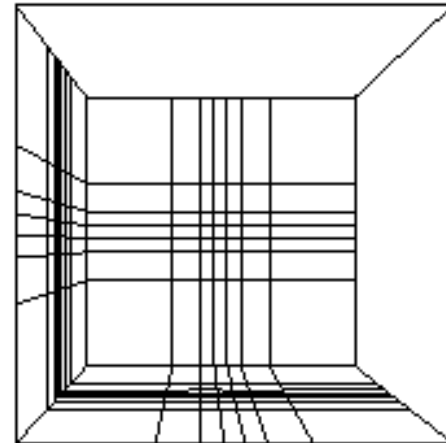
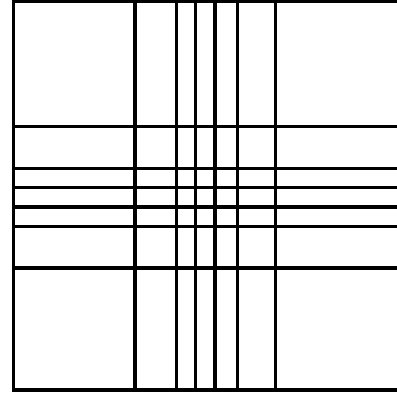
Cartesian grid

- Special case of a uniform grid: $d_x = d_y = d_z$
- Consists of squares (2D), cubes (3D)

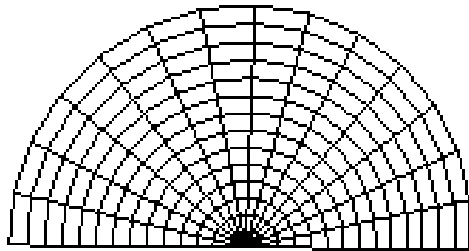


Rectilinear grids

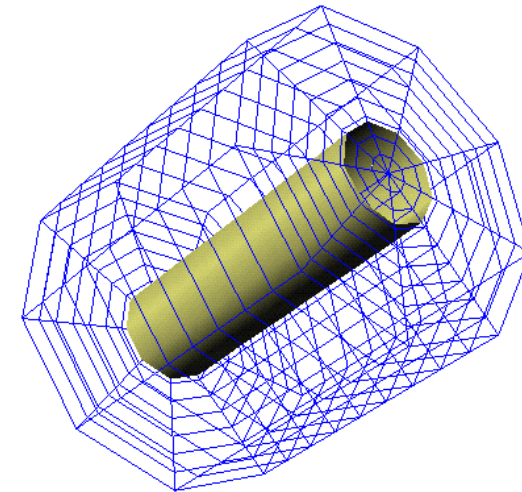
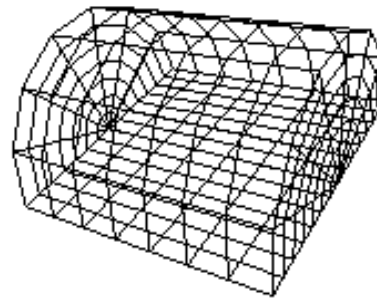
- Cells are rectangles of *different* sizes
- All grid lines are parallel to the axes
- Vertex locations are inferred from positions of grid lines for each dimension:
 - $XLoc = \{0.0, 1.5, 2.0, 5.0, \dots\}$
 - $YLoc = \{-1.0, 0.3, 1.0, 2.0, \dots\}$
 - $ZLoc = \{3.0, 3.5, 3.6, 4.1, \dots\}$
- Coordinate \rightarrow cell still quite simple



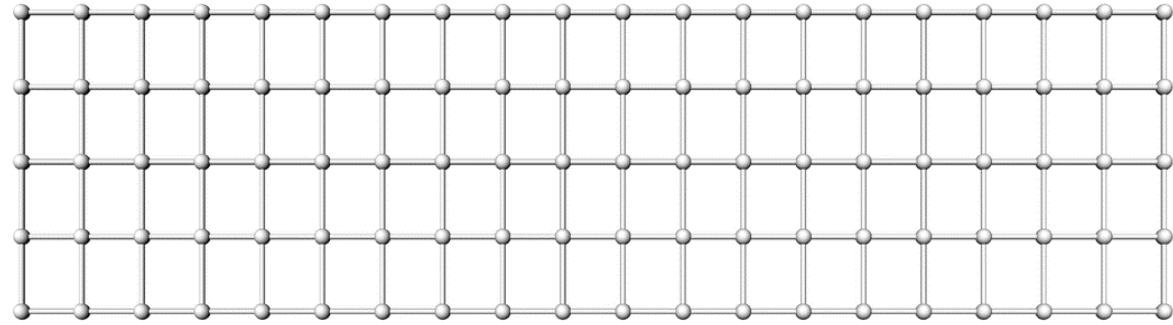
- **Curvilinear grids**
- Vertex locations are explicitly given
 - $XYZLoc = \{(0.0, -1.0, 3.0), (1.5, 0.3, 3.5), (2.0, 1.0, 3.6), \dots\}$
- Cells are quadrilaterals or cuboids
- Grid lines are not (necessarily) parallel to the axes



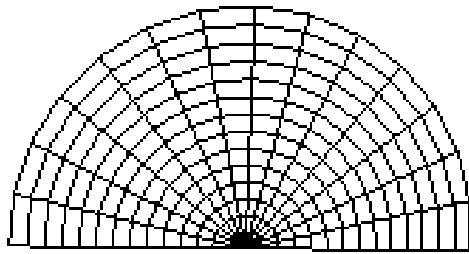
2D curvilinear grid



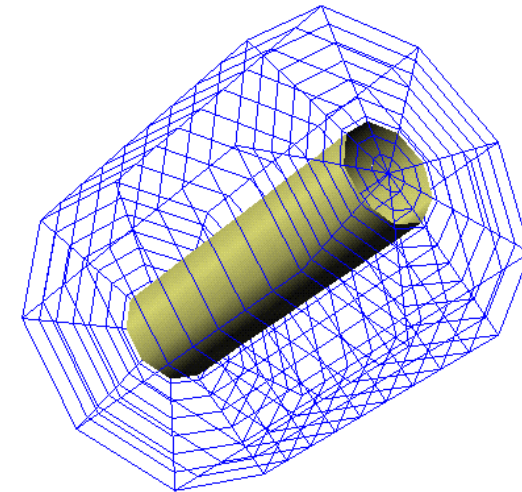
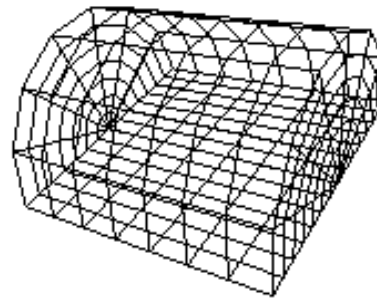
3D curvilinear grids



- **Curvilinear grids**
- Coordinate \rightarrow cell:
 - **Local search** within last cell or its immediate neighbors
 - **Global search** via quadtree/octree



2D curvilinear grid

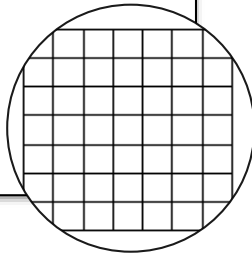


3D curvilinear grids

Data structures for structured grids

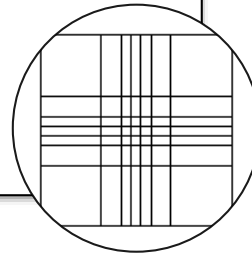
- dependent variable: array
- positions: implicit, no storage needed

**uniform
grid**



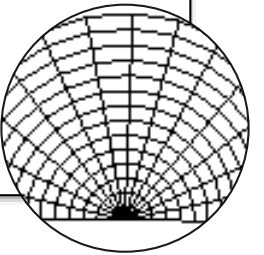
- dependent variable: array
- positions: 2/3 location vectors

**rectilinear
grid**

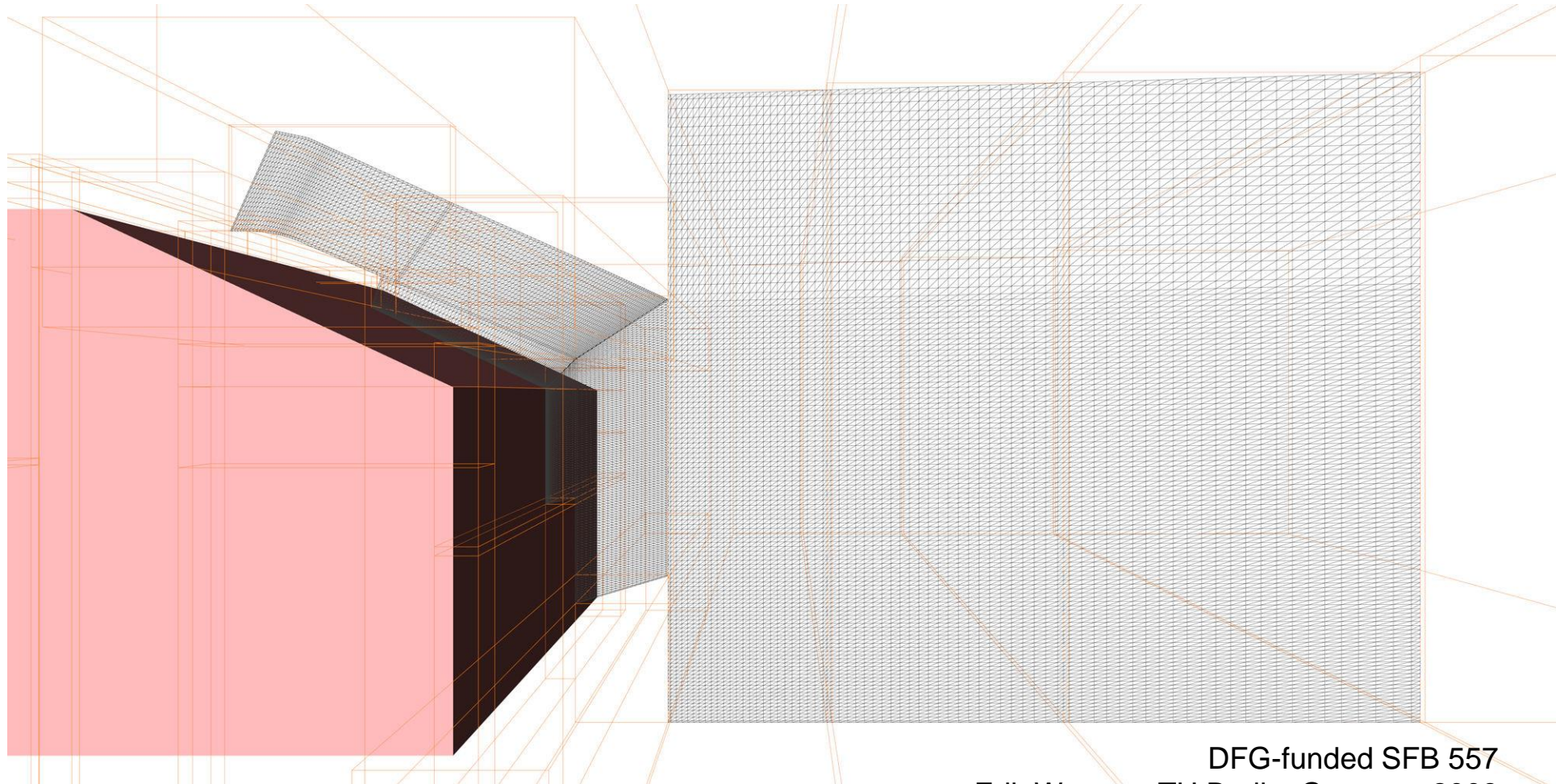


- dependent variable: array
- positions: array

**curvilinear
grid**

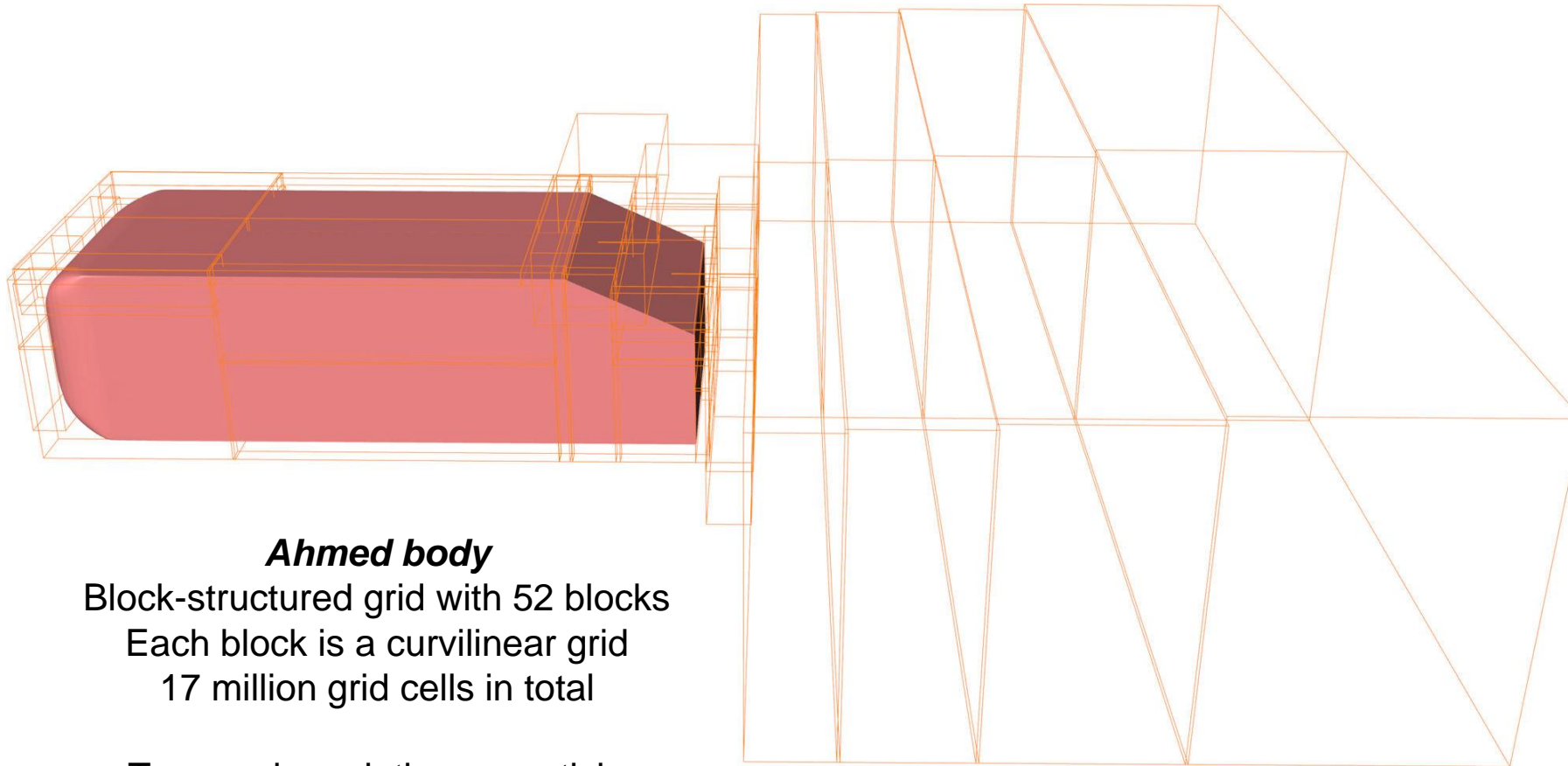


- **Block-structured grids**
- combination of several structured grids



DFG-funded SFB 557
Erik Wassen, TU Berlin, Germany 2008

- Demands on data storage, an example:



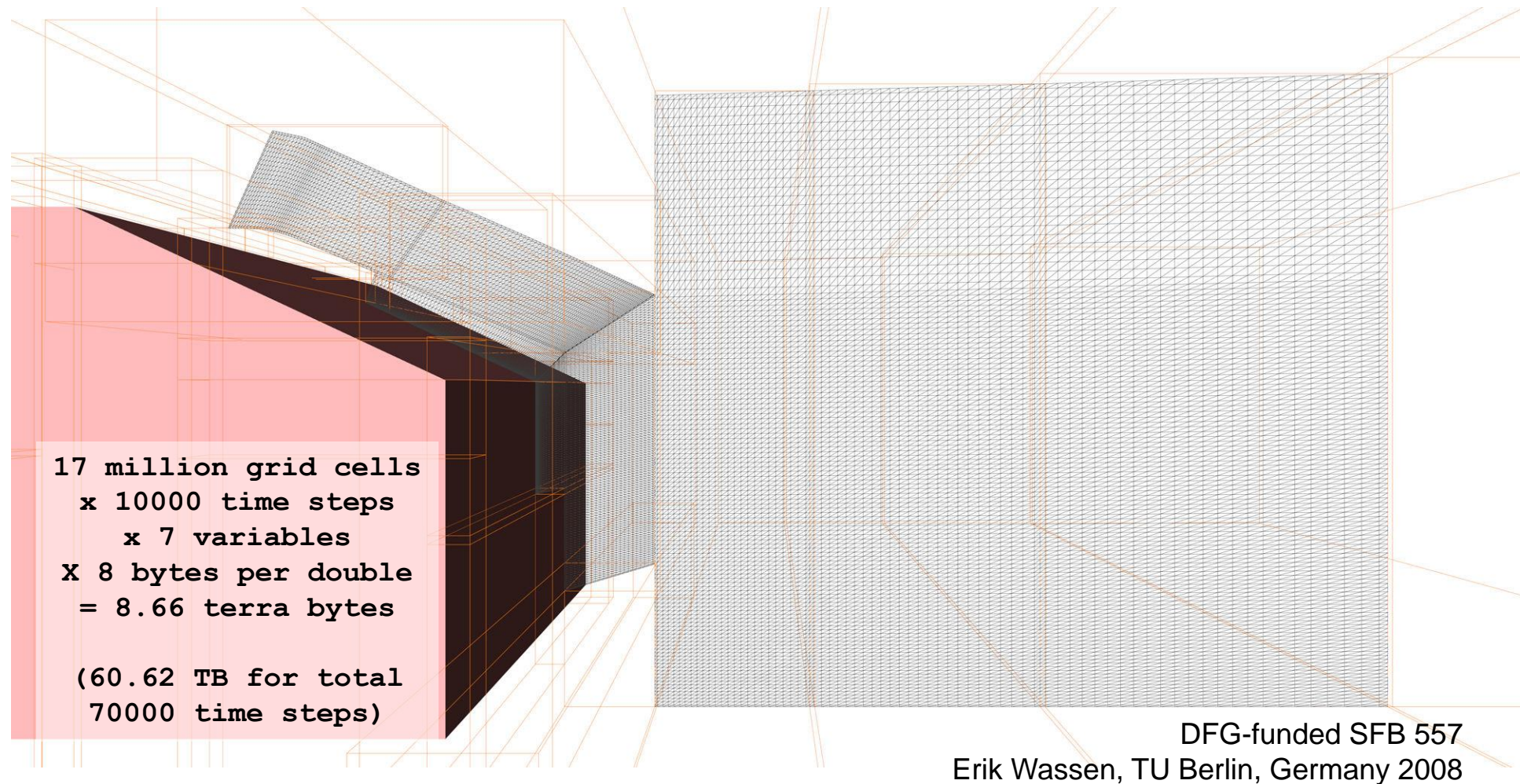
Ahmed body

Block-structured grid with 52 blocks
Each block is a curvilinear grid
17 million grid cells in total

Temporal resolution: a particle
needs 10000 time steps from front
to back of the Ahmed body

DFG-funded SFB 557
Erik Wassen, TU Berlin, Germany 2008

- Demands on data storage, an example:



➔ Do not save every time step, not every variable, and not every block.

Unstructured Grids

sample points are not laid out
in a matrix-like fashion

unstructured grids connect
neighboring samples

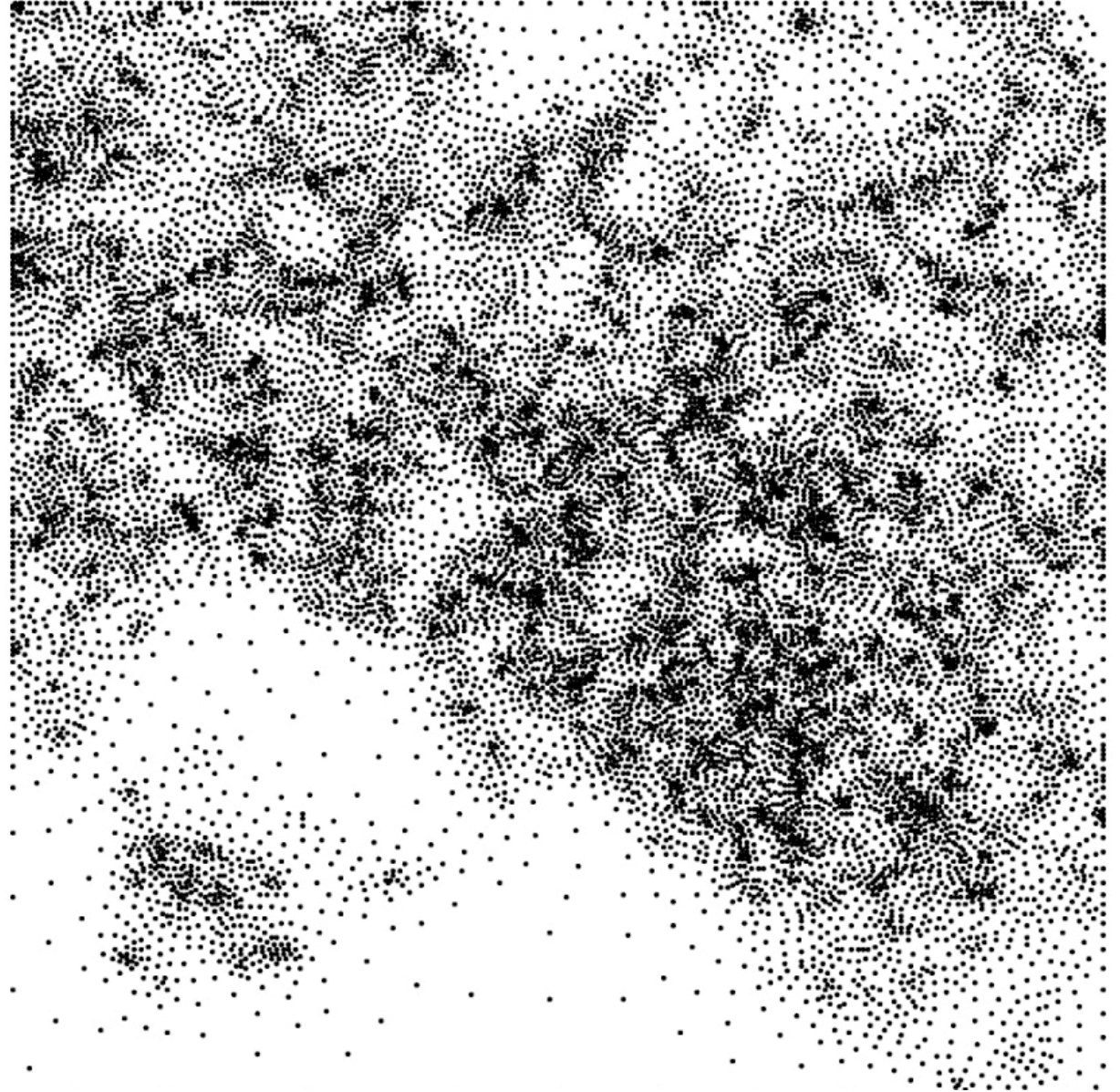
many possibilities how to do this

triangle/tetrahedral mesh

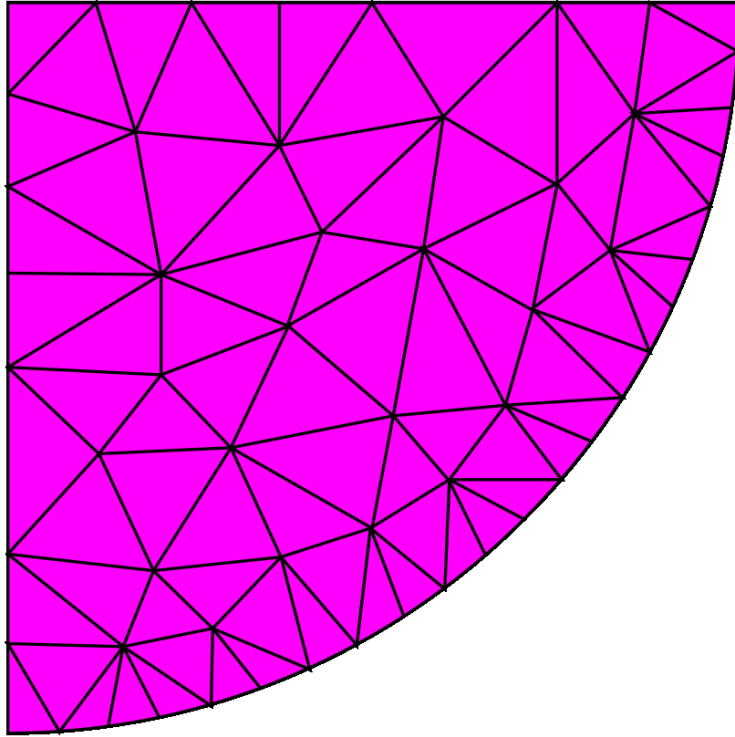
2D/3D linear cells

quad/hexahedral mesh

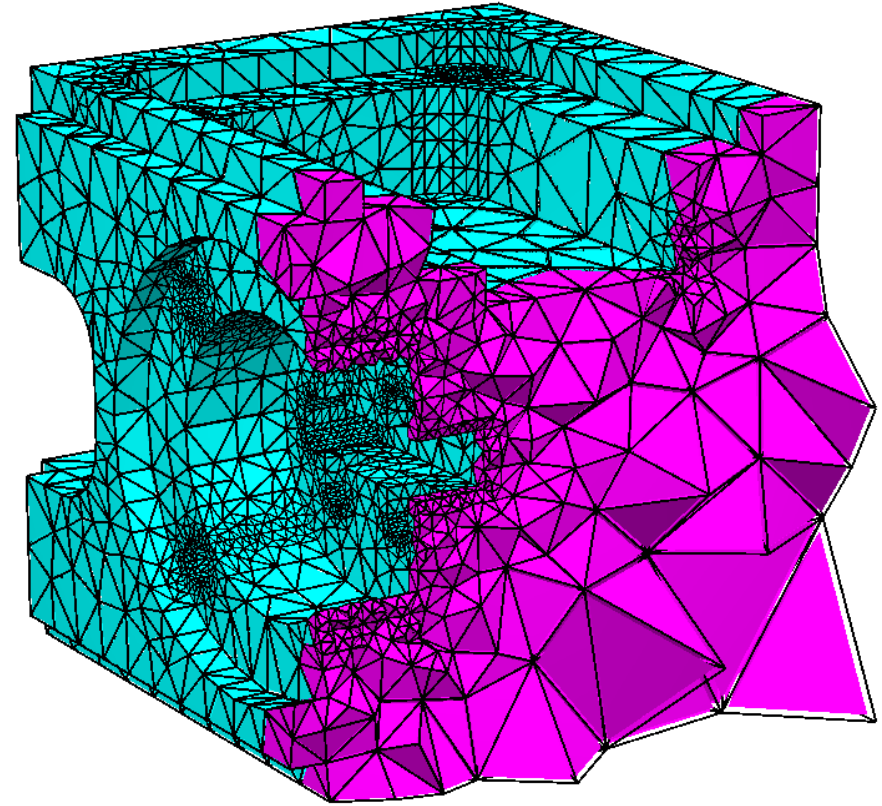
2D/3D cube-like cells



Unstructured Grids: Triangle / Tetrahedral Meshes



2D unstructured grid
consisting of triangles



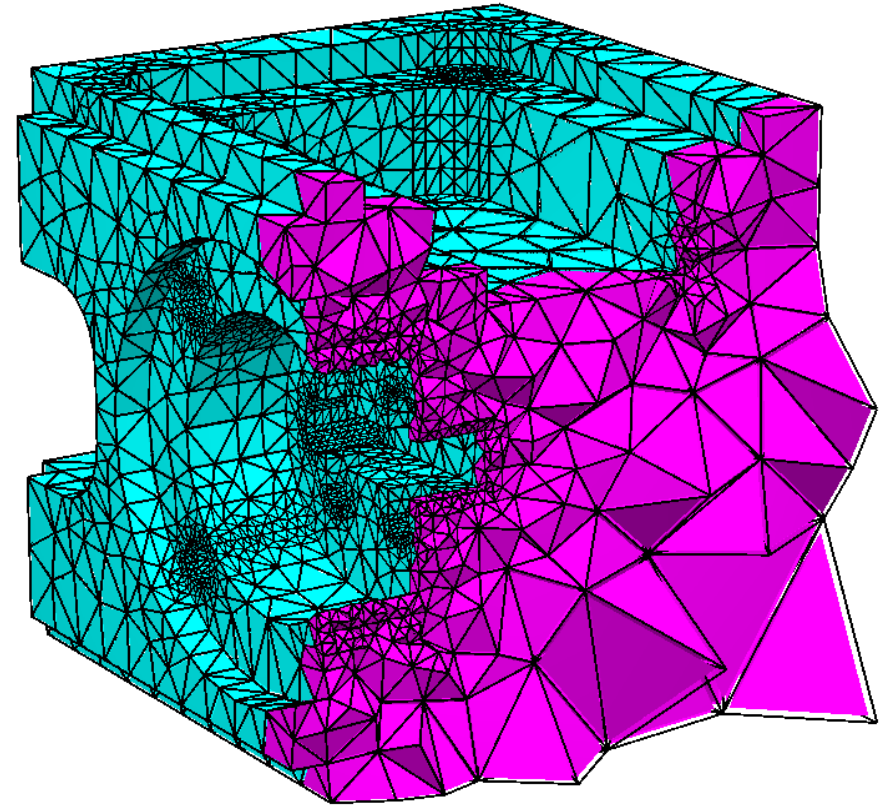
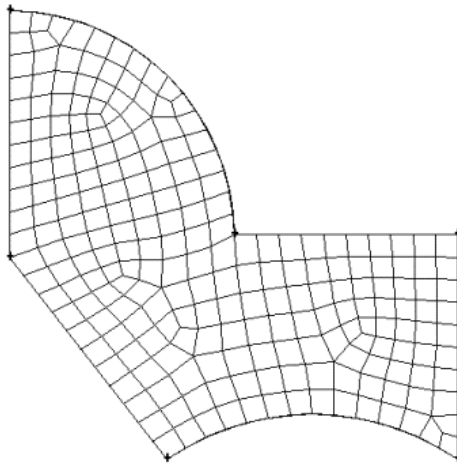
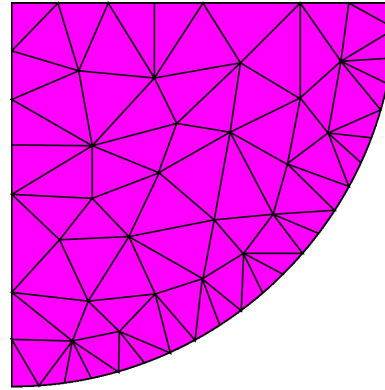
3D unstructured grid
consisting of tetrahedra
(from TetGen user manual)

Unstructured Grids

Vertex locations and connectivity explicitly given

Coordinate \rightarrow cell:

- Local search within last cell or its immediate neighbors
- Global search via quadtree/octree



Data structures for Triangles Meshes

shared vertex data structure

vertex table

stores positions

triangle table

stores indices into vertices

gives “triangle soup”

from this we can derive:

list of edges

vertex neighbors

Vertices	Triangles
$x_1 \ y_1 \ z_1$	$v_{11} \ v_{12} \ v_{13}$
...	...
$x_v \ y_v \ z_v$...
	...
	...
	$v_{F1} \ v_{F2} \ v_{F3}$

$12 \text{ B/v} + 12 \text{ B/f} = 36 \text{ B/v}$
no neighborhood info

Data structures for Triangles Meshes

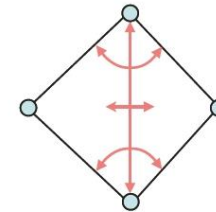
many other options exist

Vertices	Triangles
$x_1 \ y_1 \ z_1$	$v_{11} \ v_{12} \ v_{13}$
...	...
$x_v \ y_v \ z_v$...
	...
	...
	$v_{F1} \ v_{F2} \ v_{F3}$

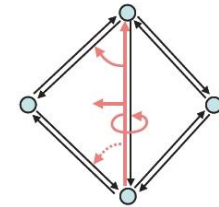
$12 \text{ B/v} + 12 \text{ B/f} = 36 \text{ B/v}$
no neighborhood info

Triangles								
$x_{11} \ y_{11} \ z_{11}$	$x_{12} \ y_{12} \ z_{12}$	$x_{13} \ y_{13} \ z_{13}$						
$x_{21} \ y_{21} \ z_{21}$	$x_{22} \ y_{22} \ z_{22}$	$x_{23} \ y_{23} \ z_{23}$						
...						
$x_{F1} \ y_{F1} \ z_{F1}$	$x_{F2} \ y_{F2} \ z_{F2}$	$x_{F3} \ y_{F3} \ z_{F3}$						

$36 \text{ B/f} = 72 \text{ B/v}$
no connectivity!

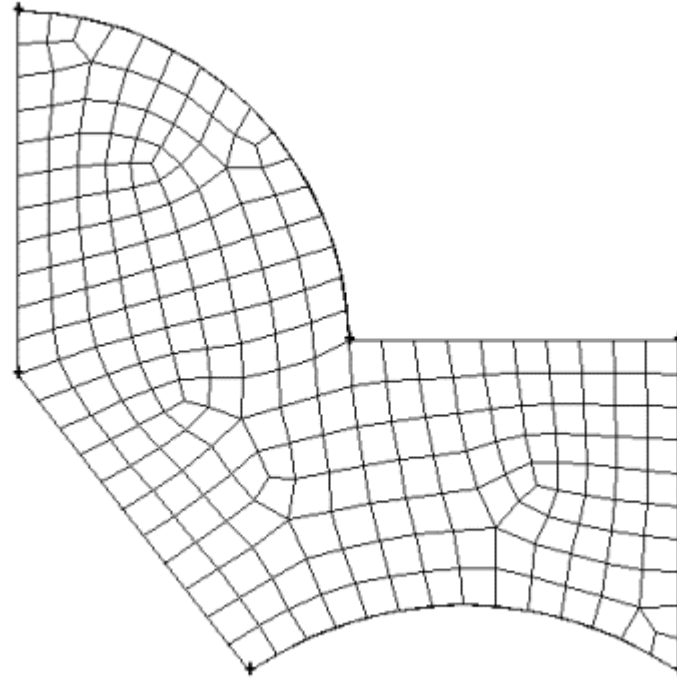


120 B/v
edge orientation?



$96 \text{ to } 144 \text{ B/v}$
no case distinctions
during traversal

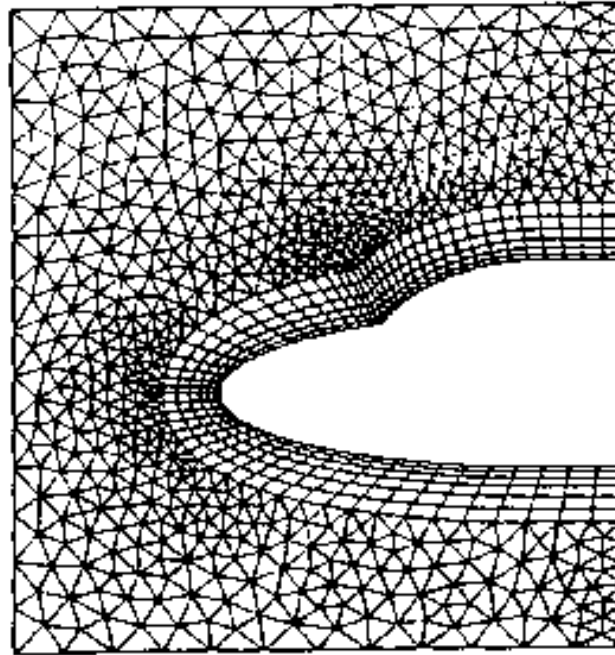
Unstructured Grids: Quad Mesh



2D unstructured grid consisting of quads

Hybrid Grids

Combination of different grid types



2D hybrid grid

Summary

- Continuous objects are often the subject of study
 - Need to be sampled to be represented in the computer
- Data is stored at samples (most often points)
- Structured grids: matrix-like organization of neighborhood
 - uniform
 - rectilinear
 - curvilinear
- Unstructured grids: arbitrary organization of neighborhood
 - triangle/tetrahedral meshes
 - quad/hexahedral meshes