# SF 1684 Algebra and Geometry Lecture 3 

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## Topics for Today

(1) Systems of Linear Equations
(2) Matrices: Definition and Row Operations

## Linear Equations

## Definition

An equation of the form $a_{1} x_{1}+a_{2} x_{2}+\cdots+a_{n} x_{n}=b$ where $a_{i} \in \mathbb{R}, b \in \mathbb{R}$ and the $x_{i}$ are variables is called a linear equation.

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If $b=0$, the equation is then called homogeneous.

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Example:

$$
n=2 \quad a_{1}=2 \quad x_{1}=x \quad b=3
$$

$$
2 x+y=3 \text { is a linear equation } \quad q_{L}=1 \quad x_{L}=y
$$

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Example:

$$
2 x+y=3 \text { is a linear equation }
$$

$x^{2}+3 y=1$ is not a linear equation
power of twro makes it not linear

## System of Linear Equations

## Definition

Having multiple linear equations

$$
q_{i, j} \in \mathbb{R}
$$

$$
m \text {-equation }\left\{\begin{array}{c}
a_{1,1} x_{1}+\underline{a_{1,2}} x_{2}+\cdots+a_{\underline{1, n}} x_{n}=\underline{b_{1}} \\
a_{2,1} x_{1}+\underline{a_{2,2}} x_{2}+\cdots+\underline{a_{2, n}} x_{n}=\underline{b_{2}} \\
\vdots
\end{array} \quad b_{j} \in \mathbb{R}\right.
$$

$$
a_{\underline{m, 1}} x_{1}+a_{\underline{m, 2}} x_{2}+\cdots+\underline{a_{m, n}} x_{n}=b_{m}
$$

is called an $m \times n$ system of linear equations.

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Having multiple linear equations

$$
\begin{gathered}
a_{1,1} x_{1}+a_{1,2} x_{2}+\cdots+a_{1, n} x_{n}=b_{1}=0 \\
a_{2,1} x_{1}+a_{2,2} x_{2}+\cdots+a_{2, n} x_{n}=b_{2}=0 \Rightarrow \text { homogeneans } \\
\vdots \\
a_{m, 1} x_{1}+a_{m, 2} x_{2}+\cdots+a_{m, n} x_{n}=b_{m} \rightleftharpoons 0
\end{gathered}
$$

is called an $m \times n$ system of linear equations. If all the $b_{j}=0$, then the system is called homogeneous.

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is called an $m \times n$ system of linear equations. If all the $b_{j}=0$, then the system is called homogeneous. If any of $b_{j} \neq 0$, the system is called non-homogeneous.

Determining the solutions (if any) of systems of linear equations is the main motivation behind this whole course.

## Example of Problems Using a System of Linear Equations

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## Question

Give two lines, $L_{1}$ and $L_{2}$, is there a point that lies on both lines?

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$$
L_{1}: 2 x+3 y=1
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Example: If line $L_{1}$ is given by the equation

$$
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and $L_{2}$ is given by the equation

$$
L_{2}: 4 x+6 y=1
$$

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and $L_{2}$ is given by the equation

$$
L_{2}: 4 x+6 y=1
$$

then determining the solutions (if any) to the $2 \times 2$ system of linear equations:

$$
2 \text { cquatiq- }\left\{\begin{array}{l}
2 x+3 y=1 \\
4 x+6 y=1
\end{array}\right.
$$

would answer our question.

## Example of Problems Using a System of Linear Equations

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Given a set of vectors $\vec{v}_{1}, \vec{v}_{2}, \ldots, \vec{v}_{m}$, can a new vector $\vec{w}$ be written as a linear combination of the $\vec{v}_{i}$ ?

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Example: Let

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\overrightarrow{v_{1}}=(1,2,3), \overrightarrow{v_{2}}=(1,0,0), \overrightarrow{v_{3}}=(0,1,1), \vec{w}=(1,5,3)
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The question is now, does there exist an $A, B, C$ such that

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(1,5,3)=A(1,2,3)+B(1,0,0)+C(0,1,1)
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(1,5,3)=A(1,2,3)+B(1,0,0)+C(0,1,1)=(A+B, 2 A+C, 3 A+C)
$$

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Given a set of vectors $\vec{v}_{1}, \vec{v}_{2}, \ldots, \vec{v}_{m}$, can a new vector $\vec{w}$ be written as a linear combination of the $\vec{v}_{i}$ ? If so, what linear combination(s)?

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$$

Thus solving the $3 \times 3$ system of linear equations

$$
3 \text { equation }\left\{\begin{array}{llll}
A+B=1 & \text { a no } & C \\
2 A+C=5 \\
3 A+C=3 & \text { a no } B \\
\text { no } & B
\end{array}\right.
$$

would answer our question.

## Matrix Representation of a Linear System

Given a system of linear equations

$$
\begin{aligned}
& a_{1,1}\left(\text { ® }_{1}\right)+a_{1,2} \times_{3}^{2} \pm \cdots \pm a_{1, n \times 2}=x_{1} \\
& a_{2,1} \not \pm a_{2,2} \text { ( }+\cdots \pm a_{2, n \times n)}=b_{2} \\
& a_{m, 1 \times 2} \pm a_{m, 2} \otimes_{2} \pm \ldots+a_{m, n} \bigotimes_{D}=b_{m}
\end{aligned}
$$

the only relevant information are the coefficients $a_{1,1}, a_{1,2}, \ldots$ and the $b_{1}, b_{2}, \ldots$.

## Matrix Representation of a Linear System

Given a system of linear equations

$$
\begin{gathered}
a_{1,1} x_{1}+a_{1,2} x_{2}+\cdots+a_{1, n} x_{n}=b_{1} \\
a_{2,1} x_{1}+a_{2,2} x_{2}+\cdots+a_{2, n} x_{n}=b_{2} \\
\vdots \\
a_{m, 1} x_{1}+a_{m, 2} x_{2}+\ldots a_{m, n} x_{n}=b_{m}
\end{gathered}
$$


the only relevant information are the coefficients $a_{1,1}, a_{1,2}, \ldots$ and the $b_{1}, b_{2}, \ldots$. Thus we condense this information into the matrix of coefficients and the $\vec{b}$-vector

$$
\left.\underset{\sim}{\mathcal{V}}:=\left(\begin{array}{cccc}
a_{1,1} & a_{1,2} & \ldots & a_{1, n} \\
a_{2,1} & a_{2,2} & \ldots & a_{2, n} \\
\vdots & \vdots & \ddots & \vdots \\
a_{m, 1} & a_{m, 2} & \ldots & a_{m, n}
\end{array}\right)\right] \text { and } \vec{b}:=\left[\begin{array}{c}
b_{1} \\
b_{2} \\
\vdots \\
b_{m}
\end{array}\right]
$$

## Augmented Matrix of a Linear System

We also care about how the matrix of coefficients behave with the $\vec{b}$-vector and so we also consider the augmented matrix:

$$
(A \mid \vec{b}):=\left(\begin{array}{cccc|c}
a_{1,1} & a_{1,2} & \ldots & a_{1, n} & b_{1} \\
a_{2,1} & a_{2,2} & \ldots & a_{2, n} & b_{2} \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
a_{m, 1} & a_{m, 2} & \ldots & a_{m, n} & b_{m}
\end{array}\right)
$$

Example

Consider the system of linear equations:

$$
\left.\begin{array}{c}
-2 x+2 y+3 z=1 \\
3 x+y+5 z=7 \\
x+y+z=1
\end{array}\right\}
$$

Then the matrix of coefficients, $\vec{b}$-vector and augmented matrix, respectively, would be:

$$
A=\left[\begin{array}{ccc}
-2 & 2 & 3 \\
3 & 1 & 5 \\
1 & 1 & 1
\end{array}\right] \quad \vec{b}=\left[\begin{array}{l}
1 \\
? \\
1
\end{array}\right] \quad(A \mid \vec{b})=\left[\begin{array}{ccc|c}
-2 & 2 & 3 & 1 \\
3 & 1 & 5 & ? \\
1 & 1 & 1 & 1
\end{array}\right]
$$

Exercise
Exercise
Given the augmented matrices

$$
(A \mid \vec{b})=\left(\begin{array}{ccc|c}
x & y & z & z \\
2 & 5 & 5 & 1 \\
3 & 9 & 6 & 3 \\
1 & 4 & 5 & 7
\end{array}\right) \quad(B \mid \vec{b})=\left(\begin{array}{ccc|c}
x_{1} & x_{2} & x_{1} & \\
1 & 0 & 0 & 3 \\
0 & 1 & 0 & 4 \\
0 & 0 & 1 & 5
\end{array}\right)
$$

write down the corresponding system of linear equations.

$$
\begin{array}{r}
2 x+5 y+5 z=1 \\
3 x+9 y+6 z=3 \\
x+4 y+5 z=7
\end{array} \quad\left\{\begin{array}{l}
1 x_{1}+0 x_{2}+0 x_{3}=3 \Rightarrow x_{1}=3 \\
0 x_{y}+1 x_{1}+0 x_{3}=4 \Rightarrow x_{2}=4 \\
0 x_{1}+0 x_{2}+1 x_{1}=5 \Rightarrow x_{3}=5
\end{array}\right]
$$

## Terminology

$$
A:=\overbrace{\left(\begin{array}{cccc}
a_{1,1} & a_{1,2} & \cdots & a_{1, n} \\
a_{2,1} & a_{2,2} & \cdots & a_{2, n} \\
\vdots & \vdots & \ddots & \vdots \\
a_{m, 1} & a_{m, 2} & \cdots & a_{m, n}
\end{array}\right)}^{n c o l v m n s}\} \text { mows. }
$$

$A$ is called an $m \times n$ matrix.

## Terminology

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\vdots & \vdots & \ddots & \vdots \\
a_{m, 1} & a_{m, 2} & \ldots & a_{m, n}
\end{array}\right)
$$

$A$ is called an $m \times n$ matrix.
$m=$ number of rows (equations)

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\end{array}\right)
$$

$A$ is called an $m \times n$ matrix.
$m=$ number of rows (equations)
$n=$ number of columns (variable) -

## Terminology

$$
\begin{gathered}
\text { j pqsition } \\
A:=\left(\begin{array}{cccc}
a_{1,1} & a_{1,2} & \cdots & a_{1, n} \\
a_{2,1} & \overrightarrow{a_{2,2}} & \ldots & a_{2, n} \\
\vdots & \vdots & a_{i j} \cdot & \vdots \\
a_{m, 1} & a_{m, 2} & \cdots & a_{m, n}
\end{array}\right) \text { ipositiav }
\end{gathered}
$$

$A$ is called an $m \times n$ matrix.
$m=$ number of rows (equations)
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$a_{i, j}$ is the number in the $i^{t h}$ row and $j^{t h}$ column.

## Terminology

$$
A:=\left(\begin{array}{cccc}
a_{1,1} & a_{1,2} & \ldots & a_{1, n} \\
a_{2,1} & a_{2,2} & \ldots & a_{2, n} \\
\vdots & \vdots & \ddots & \vdots \\
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## Terminology 2

Given an augmented matrix

$$
(A \mid \vec{b}):=\left(\begin{array}{cccc|c}
a_{1,1} & a_{1,2} & \ldots & a_{1, n} & b_{1} \\
a_{2,1} & a_{2,2} & \ldots & a_{2, n} & b_{1} \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
a_{m, 1} & a_{m, 2} & \ldots & a_{m, n} & b_{m}
\end{array}\right)
$$

we will say a vector

$$
\vec{x}=\left[\begin{array}{c}
x_{1} \\
x_{2} \\
\vdots \\
x_{n}
\end{array}\right]
$$

solves the augmented matrix if it is a solution to the corresponding system of linear equations.

## Example

We say the vector $\vec{x}=(x, y, z)=\left(-\frac{33}{4}, \frac{9}{4}, \frac{5}{4}\right)$ solves the augmented matrix

$$
(A \mid \vec{b})=\left(\begin{array}{lll|l}
2 & 5 & 5 & 1 \\
3 & 9 & 6 & 3 \\
1 & 4 & 5 & 7
\end{array}\right)
$$

since

$$
\begin{gathered}
=2 x+5 y+5 z=2\left(-\frac{33}{4}\right)+5\left(\frac{9}{4}\right)+5\left(\frac{5}{4}\right)=1 \\
=3 x+9 y+6 z=3\left(-\frac{33}{4}\right)+9\left(\frac{9}{4}\right)+3\left(\frac{5}{4}\right)=3 \\
x+4 y+5 z=\left(-\frac{33}{4}\right)+4\left(\frac{9}{4}\right)+5\left(\frac{5}{4}\right)=7
\end{gathered}
$$

## Main Motivation

As we stated before one of the main motivations behind this whole course is to find all the solutions (if any) of a given system of linear equations.

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## Question

Given an augmented matrix $(A \mid \vec{b})$ determine all vectors $\vec{x}$ that solve it or show that there are no solutions.

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## Question

Given an augmented matrix $(A \mid \vec{b})$ determine all vectors $\vec{x}$ that solve it or show that there are no solutions.

## Exercise

Find the solutions to the augmented matrix

$$
\left(\begin{array}{ccc|c}
-1 & 2 & 0 & 2 \\
2 & 1 & 2 & 21 \\
2 & -3 & 2 & 1
\end{array}\right)
$$

Exercise Solution

$$
2 x+2(-x)=2 x-2 x=0 x=0
$$

$$
\rightarrow \quad x=8, \quad y=5, z=0
$$

$$
\ddot{x}=\left[\begin{array}{l}
8 \\
5 \\
0
\end{array}\right] \quad \text { solves the }
$$ matrix.

## Equation Operations

We see that to solve the system of linear equations, we performed certain operations to transform

$$
\begin{gathered}
-x+2 y=2 \\
2 x+y+2 z=21 \\
2 x-3 y+2 z=1
\end{gathered} \quad \Longrightarrow \cdots \Longrightarrow \quad \begin{aligned}
& x=8 \\
& y=5 \\
& z=0
\end{aligned}
$$

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We performed three different types of operations on the equations:

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We performed three different types of operations on the equations:
(1) Added a multiple of one equation to the other

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We performed three different types of operations on the equations:
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(2) Interchanged two equations

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\end{gathered} \quad \Longrightarrow \cdots \Longrightarrow \quad \begin{aligned}
& x=8 \\
& y=5 \\
& z=0
\end{aligned}
$$

We performed three different types of operations on the equations:
(1) Added a multiple of one equation to the other
(2) Interchanged two equations =
(3) Multiplied an equation by a non-zero constant -

Translate to Matrices
How do these equation operations translate to matrices:
(1) Add a multiple of one equation to the other

$$
\begin{aligned}
& {\left[\begin{array}{c}
R_{1} \\
R_{2} \\
\vdots \\
R_{n}
\end{array}\right] \rightarrow\left[\begin{array}{c}
E_{1} \\
E_{1} \\
\vdots \\
E_{n}
\end{array} \quad \rightarrow \frac{E_{1}+2 G_{1}}{\vdots} \rightarrow\left[\begin{array}{c}
R_{1} \\
R_{2}+2 R_{1} \\
\vdots \\
R_{n}
\end{array}\right]\right.} \\
& \text { (3) Interchange two equations } \\
& \left.\left[\begin{array}{c}
R_{1} \\
\vdots \\
R_{n}
\end{array}\right] \rightarrow \begin{array}{ccc}
E_{1} & C E_{1} \\
\vdots & & \rightarrow \\
E_{n}
\end{array} \quad \begin{array}{ll}
E_{n}
\end{array}\right]\left[\begin{array}{c}
C_{2} R_{1} \\
R_{2} \\
R_{n}
\end{array}\right]
\end{aligned}
$$

## Row Operations

## Definition <br> Row Operations

## Row Operations

## Definition

Row Operations
(1) Add a multiple of one row to the other

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## Definition

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(1) Add a multiple of one row to the other
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## Row Operations

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Row Operations
(1) Add a multiple of one row to the other
(2) Interchange two rows
(3) Multiply a row by a non-zero constant

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(1) Add a multiple of one row to the other
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## CAUTION!!!!!!

## Row Operations

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Row Operations
(1) Add a multiple of one row to the other
(2) Interchange two rows
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## CAUTION!!!!!

These are row operations.

## Row Operations

## Definition

Row Operations
(1) Add a multiple of one row to the other
(2) Interchange two rows
(3) Multiply a row by a non-zero constant

## CAUTION!!!!!

These are row operations. We can NOT do the same the things to the columns!

## Row Operations

## Definition

Row Operations
(1) Add a multiple of one row to the other
(2) Interchange two rows
(3) Multiply a row by a non-zero constant

## CAUTION!!!!!

These are row operations. We can NOT do the same the things to the columns!

Can NOT add a multiple of one column to the other!

## Row Operations

## Definition

Row Operations
(1) Add a multiple of one row to the other
(2) Interchange two rows
(3) Multiply a row by a non-zero constant

## CAUTION!!!!!

These are row operations. We can NOT do the same the things to the columns!

Can NOT add a multiple of one column to the other! Can NOT interchange two columns!

## Row Operations

## Definition

## Row Operations

(1) Add a multiple of one row to the other
(2) Interchange two rows
(3) Multiply a row by a non-zero constant

## CAUTION!!!!!

These are row operations. We can NOT do the same the things to the columns!

Can NOT add a multiple of one column to the other! Can NOT interchange two columns!
Can NOT multiply a column by a non-zero constant!

## Exercise

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Use matrices and row operations to find the solution to the system of linear equations

$$
\begin{gathered}
x+y+2 z=9 \\
2 x+4 y-3 z=1 \\
3 x+6 y-5 z=0
\end{gathered} \quad \Longrightarrow\left[\begin{array}{l}
x=c \\
y=b \\
z=c
\end{array}\right]
$$

$$
\left[\begin{array}{ccc|c}
1 & 1 & 2 & 9 \\
2 & 4 & -3 & 1 \\
3 & 6 & -5 & 0
\end{array}\right] \underset{\substack{\text { paw } \\
\text { operations }}}{\Longrightarrow}\left[\begin{array}{lll|l}
1 & 0 & 0 & a \\
0 & 1 & 0 & b \\
0 & 0 & 1 & c
\end{array}\right]
$$

Extra Work Space

$$
\begin{aligned}
& {\left[\begin{array}{cc|c}
-1 & 1_{1}^{\prime} & 2 \\
24 & 9 \\
24 & -3 & 1 \\
36 & -5 & 0
\end{array}\right] \begin{array}{ccc|c}
R_{-}-2 R_{1} \\
R_{3}-3 R_{1}
\end{array}\left[\begin{array}{ccc|c}
1 & 1 & 2 & 9 \\
0 & 2 & -7 & -17 \\
0 & 3 & -11 & -27
\end{array}\right] \frac{\frac{1}{2} E_{2}}{}\left[\begin{array}{ccc|c}
1 & 1 & 2 & 9 \\
0 & 1 & -3.5 & -9.5 \\
0 & 3 & -4 & -27
\end{array}\right]} \\
& R_{1}-R_{2}\left[\begin{array}{ccc|c}
1 & 0 & 5.5 & 18.5 \\
0 & 1 & -3.5 & -9.5 \\
0 & 0 & 0.5 & 1.5
\end{array}\right] 2 R_{3}\left[\begin{array}{ccc|c}
1 & 0 & 5.5 & 18.5 \\
0 & 1 & -3.5 & -9.5 \\
0 & 0 & 1 & 3
\end{array}\right] \\
& \begin{array}{l}
R_{1}-S . S R_{3} \\
R_{1}+3 . S R_{3}
\end{array}\left[\begin{array}{ccc|c}
1 & 0 & 0 & 2 \\
0 & 1 & 0 & 1 \\
0 & 0 & 1 & 3
\end{array}\right] \rightarrow \begin{array}{c} 
\\
\\
0+0 y+0 z=2 \\
0 x+1 y+0 z=1 \\
0 x+0 y+(z=3
\end{array} \\
& 112 \\
& \begin{array}{ll}
021 \\
0 & 1
\end{array} \\
& \rightarrow x=2, y=1, z=3
\end{aligned}
$$

## Homogeneous Solutions

## Definition

Given a matrix $A$, we say that $\vec{x}$ is a homogeneous solution of $A$ if it solves the augmented matrix $(A \mid \overrightarrow{0})$.

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(1) $\overrightarrow{0}$ is a homogeneous solution
(2) If $\vec{x}$ is a homogeneous solution and $c \in \mathbb{R}$ then $c \vec{x}$ is also a homogeneous solution

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(1) $\overrightarrow{0}$ is a homogeneous solution, $\overrightarrow{0}$ is called the trivial
(2) If $\vec{x}$ is a homogeneous solution and $c \in \hat{R}^{\text {homgen }}$ thens) $\vec{x}$ is is alion a homogeneous solution
(3) If $\vec{x}$ and $\vec{y}$ are homogeneous solutions than so is $\vec{x}+\vec{y}$

Proof

1) $\vec{O}$ is a momagens solution

$$
-a_{11} x_{1}+\cdots+\xi_{n} x_{1}=0
$$

茄:
Ye, $\vec{O}$ is a solotion

$$
a_{m 1} x_{1} \vdash-+a_{m n} x_{n}=0
$$

2) $\bar{x}$ is a homogerivs then $\vec{x}=\left[\begin{array}{c}x_{1} \\ \vdots \\ x_{n}\end{array}\right]$ and salve) **), $C \in \mathbb{R}$
$c \vec{x}=\left[x_{1}\right]$

$$
\begin{aligned}
& \left.C \vec{x}=\left[\begin{array}{c}
c x_{1} \\
\vdots \\
x_{1}
\end{array}\right], \quad \begin{array}{rl}
a_{11}\left(c x_{1}\right)+\cdots+a_{1 n}\left(c x_{1}\right) & =c\left(a_{11} x_{1}+\cdots+q_{1 n} x_{1}\right) \\
\Rightarrow \quad c \vec{x} \text { is a homngenenus } & =c-0=0
\end{array}\right) . \quad \text { olction }
\end{aligned}
$$

3) $\vec{x}, \bar{y}$ an homogeneous soltions. $\quad \dot{x}=\left[\begin{array}{c}x_{1} \\ x_{1}\end{array}\right], y=\left[\begin{array}{l}x_{1} \\ \vdots \\ y_{n}\end{array}\right]$

$$
\begin{aligned}
& \hat{x}+\vec{y}=\left[\begin{array}{l}
x_{1}+y_{1} \\
\vdots \\
x_{n}+y_{1}
\end{array}\right], \begin{array}{c}
a_{11}\left(x_{1}+y_{1}\right)+\cdots+a_{1 n}\left(x_{n}+y_{n}\right) \\
-\underbrace{a_{11} x_{1}+\ldots a_{1 n} x_{n}}_{=c}+\underbrace{a_{11} y_{1}+-a_{1 n} y_{n}}_{=c}=0+c=0
\end{array}=0 \text { homogenean sqution. }
\end{aligned}
$$

Theorem
Given an augmented matrix $(A \mid \vec{b})$ and any vector $\vec{x}_{0}$ that solves the augmented matrix, then all vectors that solve the matrix will be of the form

$$
\vec{x}+\vec{x}_{0}
$$

where $\vec{x}$ is a homogeneous solution of $A$.
Proof Suppose $(A \mid \vec{b}) \longrightarrow$

$$
\begin{gathered}
a_{11} x_{1}+\cdots+a_{1 n} x_{3}=b_{1} \\
\vdots \\
a_{n} x_{1} \ldots a_{m n} x_{n}=b_{n}
\end{gathered}
$$

$\vec{y}$ is a solution to $(\mathbb{R} \mid \vec{b})$. Want to show that

$$
\left[\begin{array}{l}
\ddot{y} \\
\vdots \\
\dot{x}
\end{array}\right] \quad \begin{aligned}
& \vec{y}=\vec{x}+\vec{x}_{0} \text { where } \vec{x} \text { is a homage emus. } \\
& \text { Enough to show } \vec{x}=\vec{y}-\vec{x}_{0} \text { is a homage }
\end{aligned}
$$

Extra Work Space

$$
\Rightarrow \quad \bar{y}-\vec{x}_{0}=\bar{x} \text { is a homogeneous } \Rightarrow \vec{y}=\vec{x}+\vec{x}_{0}
$$

$$
\begin{aligned}
& \text { So if } \vec{y}=\left[\begin{array}{c}
y_{1} \\
\vdots \\
x_{0}
\end{array}\right] \text { \& } \vec{x}_{0}=\left[\begin{array}{c}
z_{1} \\
\vdots \\
z_{1}
\end{array}\right] \text { is a gif } \begin{array}{l}
\text { solution. }
\end{array} \\
& =a_{11} y_{1}+\cdots+a_{1 n} y_{n}=b_{1} \quad-a_{11} z_{1}+\cdots+a_{n} z_{n}=b_{1} \\
& a_{m 1} y_{1} \ldots a_{m n} y_{n}=b_{n} \quad a_{m n} z_{1}+\ldots a_{m}, z_{m_{n}}=b_{m} \\
& \vec{y}-\vec{x}_{2}=\left[\begin{array}{c}
y_{1}-z_{1} \\
\vdots \\
y_{n}-z_{n}
\end{array}\right] \\
& a_{11}\left(y_{1}-z_{1}\right)+\cdots+a_{n n}\left(y_{n}-z_{n}\right)=a_{11} y_{1}+\cdots a_{n n} y_{n}-\left(a_{1}, z_{1}+\cdots a_{n}, z_{n}\right) \\
& =b_{1}-b_{1}=0
\end{aligned}
$$

## 0,1 , or $\infty$ Solution

## Theorem

Any augmented matrix $(A \mid \vec{b})$ either has
(1) No solutions
(2) Exactly 1 solution
(3) Infinitely many solutions

## Extra Work Space

